

(Not so) Brief Review of GTR

In STR: $\cancel{ds^2} \quad s^2 = \eta_{\mu\nu} x^\mu x^\nu$

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What if
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 $g_{\mu\nu}(x)$

→ The invariant length element:

$$ds^2 = \underbrace{g_{\mu\nu}(x)} dx^\mu dx^\nu$$

describes a spacetime geometry different from Minkowski.

→ A general curved manifold is called "Riemannian".

→ Equivalence principle: Locally, the manifold is Minkowski so that "local Lorentz transformation" connects the coordinate frames.

(Proof: p149 - Schwartz -

$$\begin{aligned} g_{\mu\nu}(x) dx^\mu dx^\nu &= g_{\alpha\beta}(x') dx'^\alpha dx'^\beta \\ &= g_{\alpha\beta}(x') \frac{\partial x'^\alpha}{\partial x^\rho} dx^\rho \frac{\partial x'^\beta}{\partial x^\sigma} dx^\sigma \\ &= \left(g_{\alpha\beta}(x') \frac{\partial x'^\alpha}{\partial x^\rho} \frac{\partial x'^\beta}{\partial x^\sigma} \right) dx^\rho dx^\sigma \end{aligned}$$

⇒ $\boxed{g_{\mu\nu}(x) = g_{\alpha\beta}(x') \frac{\partial x'^\alpha}{\partial x^\mu} \frac{\partial x'^\beta}{\partial x^\nu}}$ ← generalizir $\Lambda_{\rho}^{\alpha} !!$

(1)

For consistency in notations, let's denote

$$\frac{\partial x^{\alpha'}}{\partial x^{\beta}} \equiv \Lambda^{\alpha'}_{\beta}$$

→ It is easy to show that

~~$$\frac{\partial x^{\alpha}}{\partial x^{\beta'}}$$~~

$$\equiv$$

$$\Lambda^{\alpha}_{\beta'} = \left(\Lambda^{\alpha'}_{\beta} \right)^{-1} \quad \underline{\underline{H/W}}$$



* The space in which this general metric $g_{\mu\nu}(x)$ is defined is called a "Riemannian Manifold".



Show that for a symmetric matrix A with components $\in \mathbb{R}$, \exists matrix H s.t. $H^T A H$ is diagonal with eigenvalues of A .

→ Using the above theorem:

For a $g_{\alpha'\beta'}(x)$, $\exists \Lambda^{\alpha'}_{\beta}$ s.t.

$$\Lambda^{\alpha'}_{\beta} g_{\alpha'\beta'} \Lambda^{\beta'}_{\alpha} = \eta_{\beta\alpha} = \eta_{\alpha\beta} = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & \ddots & \\ & & & 1 \end{pmatrix}$$

→ Physical implication:

The above result implies, that at every "local" point in spacetime, x^μ , with a global metric $g_{\mu\nu}(x)$ it is possible to define (transform) a Minkowski metric valid in the neighbourhood of x^μ .

⇒ "The local flatness"

→ The corresponding local frame is called the "local Lorentz frame".

→ Locally flat coordinate system:

[skipping mathematical details outside the scope of this course; Read Schutz Sec. 6.2, p149]

→ Given any point P on the Riemannian manifold, a coordinate system x^α can be found whose origin is at P and:

$$g_{\alpha\beta}(x) = \eta_{\alpha\beta} + O(x^\mu x_\mu)$$

Or

$$g_{\alpha\beta}(P) = 0 \quad ; \quad \frac{\partial}{\partial x^\gamma} g_{\alpha\beta}(P) = 0 \quad \forall \alpha, \beta, \gamma$$

But, $\frac{\partial^2}{\partial x^\gamma \partial x^\mu} g_{\alpha\beta}(P) \neq 0$ in general.

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~~Weak~~ "Condition for local flatness"

→ The principles of General Relativity:

(I) Spacetime, which is a set consisting of all events, is a four-dimensional manifold whose geometry is described by a metric.

(II) The metric is measurable by rods and clocks. The distance along a rod between two nearby points is $|\vec{dx} \cdot \vec{dx}|^{1/2}$ and the time measured by a clock that experiences two events closely separated in time is $|-d\vec{x} \cdot d\vec{x}|^{1/2}$

→ timelike ($ds^2 < 0$)
→ spacelike ($ds^2 > 0$)

→ There do not exist ^(global) coordinates in which $d\vec{x} \cdot d\vec{x} = ds^2 = -dt^2 + dx^i{}^2$ everywhere.

(III) The metric of spacetime can be put in the Lorentz form $\eta_{\alpha\beta}$ at any particular event by an appropriate choice of coordinates.

→ The above three statements/principles specify the geometry.

(IV) How do particles/fields/fluids behave in this "curved" geometry.

→ (IV) The Weak equivalence principle:

"Freely falling particles move on timelike geodesics of the spacetime"

→ No other interactions except gravity.

Q How about fluids?

(V) Einstein equivalence principle — a generalization of weak equivalence principle.

"Any local physical experiment not involving gravity will have the same result if performed in a freely falling inertial frame as if it were performed in the flat spacetime of STR."

→ Does not involve fields.

→ The statement of the local Lorentz frame.

→ Next, we look at implications of GR.

→ The covariant differentiation.

→ In a general Riemannian manifold, the concepts of derivatives, translation, etc. get difficult to describe.

→ Fortunately we have a connection to the Minkowski spacetime (at least locally) to help our understanding.

→ Consider, a local Lorentz frame at point P & a vector V^α :

$$\frac{\partial V^\alpha}{\partial x^\beta} \equiv V^\alpha{}_{;\beta} \leftarrow \text{our notation for derivative.}$$

||y, consider the derivative of metric in this frame:

$$g_{\mu\nu, \alpha} = \boxed{\eta_{\mu\nu, \alpha} = 0} \leftarrow \text{identically zero!!}$$

⇒ Because this a tensor equation, and since at each point P in the global manifold with metric $g_{\alpha\beta}$ \exists a local frame with metric $\eta_{\alpha\beta}$, it must be possible to generalize this "locally valid" equation to be "globally true" or "covariant" !!

→ However, in general

$$\frac{\partial}{\partial x^\mu} g_{\alpha\beta}(x) \neq 0 !!$$

⇒ We define a so-called "covariant derivative" such that,

$$\nabla_\mu g_{\alpha\beta} \equiv \boxed{g_{\alpha\beta;\mu} = 0} \text{ for all basis.}$$

→ With appropriate tensor calculus, (which we skip due to shortage of time in this course), [Read Chap. 5 from Schutz]

it can be shown that:

$$\boxed{g_{\alpha\beta;\mu} \equiv g_{\alpha\beta,\mu} - \Gamma^\nu_{\alpha\mu} g_{\nu\beta} - \Gamma^\nu_{\beta\mu} g_{\alpha\nu}}$$

where, new quantities " Γ " called the "Christoffel connections" are introduced.

→ The Christoffel connections:

$$\boxed{\Gamma^\alpha_{\mu\nu} \equiv \frac{1}{2} g^{\alpha\beta} (g_{\beta\mu,\nu} + g_{\beta\nu,\mu} - g_{\mu\nu,\beta})}$$

$$\rightarrow \boxed{\Gamma^\alpha_{\mu\nu} = \Gamma^\alpha_{\nu\mu}}$$

H/W How do $\Gamma^\alpha_{\mu\nu}$ transform under GCT? Is it a tensor?