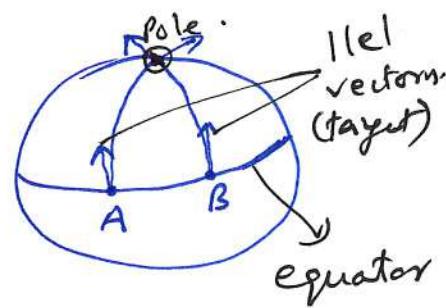


Q Why do we need to change the notion of a derivative in a curved spacetime?
 → Parallel transport — A demonstration of the inadequacy of std. derivative!

Case - I: Two parallel lines never intersect in flat space.

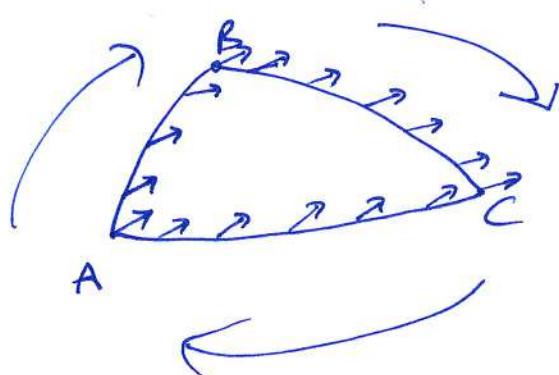
→ But on a sphere, two parallel vectors along the equator will intersect at the pole!!



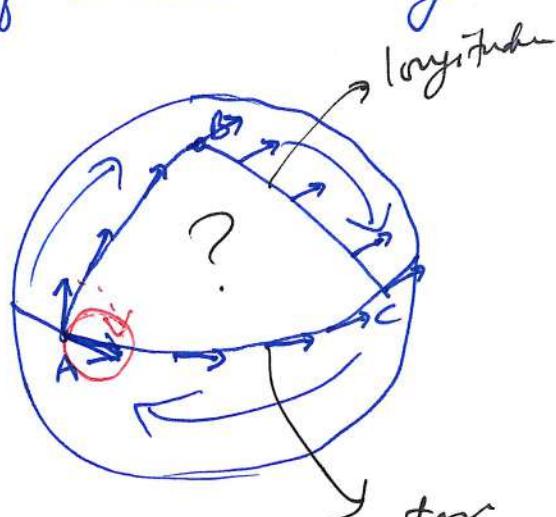
↓
Not flat

→ Called the "intrinsic curvature" of a $(n-1)$ D space enclosed in n -D manifold.

Case - II: Parallel transport of a vector along a closed path.



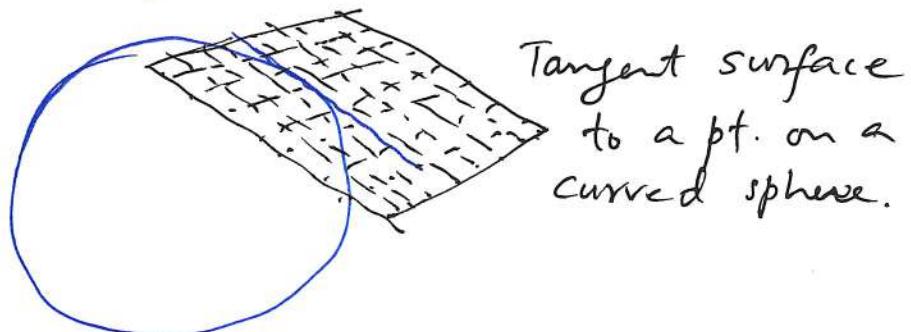
Flat space
(Intrinsically flat)



sphere
(intrinsically curved
2D surface.)
embedded in 3D space.

→ We note that :

- ⊗ In curved space, the result of parallel transporting a vector from one point to another depends on the path taken.
- ⊗ Two vectors can only be compared in a natural way if they are elements of the same tangent space.



* So, two particles moving by each close to each other can have well defined rel. vel. but e.g. two galaxies moving wrt. each other can't have a well defined rel. velocity

→ ∴ The perceived redshift of galaxies is not because they are receding, but because the universe is expanding!

In fact we can't comment on it since rel. vel. can't be defined.

Parallel transport in a curved spacetime.

→ Consider an arbitrary tensor $T^{\mu_1 \mu_2 \dots \mu_k}_{\nu_1 \dots \nu_l}$

to be transported along a curve $x^\mu(\lambda)$.

→ The requirement for parallel transport, in flat space:

$$\boxed{\frac{d}{d\lambda} T^{\mu_1 \dots \mu_k}_{\nu_1 \dots \nu_l} = \frac{dx^\mu}{d\lambda} \frac{\partial}{\partial x^\mu} T^{\mu_1 \dots \mu_k}_{\nu_1 \dots \nu_l} = 0}$$

→ To find Note: The above tensor eq. is a diff. eq. in flat spacetime, and we need to generalize this eq. (covariantly) to curved spacetime!!.

⇒ Using the covariant derivative, one can generalize parallel transport eq. to curved manifold.

$$[\text{Recall: } \cancel{g_{\mu\nu,\alpha}} \eta_{\mu\nu,\alpha} = 0 \rightarrow g_{\mu\nu,\alpha} = 0]$$

$$\Rightarrow \frac{d}{d\lambda} T^{\mu_1 \dots \mu_k}_{\nu_1 \dots \nu_l} \cancel{\rightarrow} \frac{D}{d\lambda} T^{\mu_1 \dots \mu_k}_{\nu_1 \dots \nu_l} = \frac{dx^\mu}{d\lambda} \nabla_\mu T^{\mu_1 \dots \mu_k}_{\nu_1 \dots \nu_l}$$

where, we have defined a directional covariant derivative:

$$\boxed{\frac{D}{d\lambda} \equiv \frac{dx^\mu}{d\lambda} \nabla_\mu}$$

$$\Rightarrow \boxed{\frac{dx^\sigma}{d\lambda} \nabla_\sigma T^{\mu_1 \dots \mu_n}_{\nu_1 \dots \nu_n} = 0} \quad \text{← Equation of parallel transport.}$$

Case: A vector v^μ :

Then, $\nabla_\sigma v^\mu = \frac{\partial}{\partial x^\sigma} v^\mu + \Gamma_{\sigma\gamma}^\mu v^\gamma$

$$\Rightarrow \frac{dx^\sigma}{d\lambda} \nabla_\sigma v^\mu = \boxed{\frac{d}{d\lambda} v^\mu + \Gamma_{\sigma\gamma}^\mu \frac{dx^\sigma}{d\lambda} v^\gamma = 0}$$

↑
Eq. of parallel transport for a vector!!

Case: The metric $g_{\mu\nu}$:

Q What is the parallel transport of metric?

$$\frac{D}{d\lambda} g_{\mu\nu} = \boxed{\frac{dx^\sigma}{d\lambda} \nabla_\sigma g_{\mu\nu} = 0 + g_{\mu\nu}}$$

↑
Identically true!!

H/W Show that if two vectors v^μ & w^ν are parallel transported, then their inner product (scalar product/contraction) is preserved.
i.e. $\frac{d}{d\lambda} (v_\mu w^\mu) = 0$

Next step: Generalizing the straight line to curved manifold!

The path of shortest distance between two points.

A path that parallel-transports its own tangent vector.

→ The tangent vector to a path $x^\mu(\lambda)$:

$$v^\mu \equiv \frac{dx^\mu}{d\lambda}$$

⇒ Parallel transport eq. of tangent vector:

$$\frac{D}{d\lambda} v^\mu = \boxed{\frac{D}{d\lambda} \frac{dx^\mu}{d\lambda} = 0}$$

$$\Rightarrow \frac{dx^\mu}{d\lambda} \nabla_\lambda \left(\frac{dx^\mu}{d\lambda} \right) = 0$$

$$\Rightarrow \cancel{\frac{dx^\mu}{d\lambda}} \frac{\partial}{\partial x^\mu} \left(\frac{dx^\mu}{d\lambda} \right) + \Gamma_{\rho\sigma}^\mu \left(\frac{dx^\sigma}{d\lambda} \right) \left(\frac{dx^\rho}{d\lambda} \right) = 0$$

$$\Rightarrow \boxed{\frac{d^2 x^\mu}{d\lambda^2} + \Gamma_{\rho\sigma}^\mu \frac{dx^\sigma}{d\lambda} \frac{dx^\rho}{d\lambda} = 0}$$

Geodesic equation.

(*) The curve $x^\mu(\lambda)$ is called the "geodesic".

H/W: Solve the geodesic equation for Minkowski spacetime.

→ An alternative derivation (understanding) of the geodesic equation:

How do we define distance in Riemannian spacetime?

→ The invariant length element!

$$d\tau^2 = g_{\mu\nu} dx^\mu dx^\nu = dx_\mu dx^\mu$$

$$\Rightarrow d\tau = \sqrt{g_{\mu\nu} dx^\mu dx^\nu}$$

$$\Rightarrow \int d\tau = \int \sqrt{g_{\mu\nu} \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda}} d\lambda$$

$$\Rightarrow \tau = \int d\lambda \sqrt{g_{\mu\nu} \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda}}$$

~~For~~ Consider a time-like trajectory.

⇒ $\tau \rightarrow$ proper time.

$$\& \tau^2 < 0$$

$$\Rightarrow \tau = \int d\lambda \sqrt{-g_{\mu\nu} \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda}}$$

Q What is the extremum path (trajectory) of a "test" particle represented by the dynamical variable $x^\mu(\tau)$?



Sound familiar!?
[Least Action principle!!]

\therefore Considering this "action" of a free particle

$$\mathcal{I} = \int d\lambda \sqrt{-g_{\mu\nu} \frac{dx^\mu}{d\lambda} \frac{dx^\nu}{d\lambda}}$$

If, we replace $\lambda \rightarrow \tau$ (proper time)

$$\Rightarrow \mathcal{I} = \int d\tau \sqrt{-g_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau}}$$

\downarrow

$$g_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} = g_{\mu\nu} u^\mu u^\nu$$

$$= u_\mu u^\mu$$

$\boxed{\text{4-velocity}}$ ←

Now,

$$\therefore dx_\mu dx^\mu = d\tau^2 < 0$$

$$\Rightarrow \frac{dx_\mu}{d\tau} \frac{dx^\mu}{d\tau} = -1 \Leftrightarrow \boxed{u_\mu u^\mu = -1}$$

→ Coming back to the integral,
Using the variational principle :

$$\delta I = \int d\tau \delta \sqrt{-g_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau}}$$

↓
 $u_\mu u^\mu$ ← Scalar !!
 |||
 f

$$\therefore \delta \sqrt{-f} = \frac{1}{2} (-f)^{-\frac{1}{2}} \delta f$$

$$\Rightarrow \delta \sqrt{-g_{\mu\nu} u^\mu u^\nu} = \frac{1}{2} \frac{1}{\sqrt{-g_{\mu\nu} u^\mu u^\nu}} \delta \left(g_{\mu\nu} u^\mu u^\nu \right)$$

Now,

$$\begin{aligned} \delta \left(g_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} \right) &= (\delta g_{\mu\nu}) \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} + g_{\mu\nu} \frac{d}{d\tau} \delta x^\mu \frac{dx^\nu}{d\tau} \\ &\quad + g_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{d}{d\tau} (\delta x^\nu) \end{aligned}$$

Here,
 $\delta g_{\mu\nu}(x) = g_{\mu\nu,\rho} \delta x^\rho$

~~→ Rewriting τ as the Action of free particle:~~

~~$S = \frac{1}{2} \int dI$~~

→ Therefore, substituting in $\delta\tau$:

$$\delta\tau = \frac{1}{2} \int d\tau \delta \left(g_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} \right) = 0 \quad [\text{variational principle}]$$

$$\Rightarrow \frac{1}{2} \int d\tau \left[\underbrace{\frac{\partial g_{\mu\nu}}{\partial x^\rho} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} \delta x^\rho}_{+ g_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{d}{d\tau} \delta x^\nu} \right] = 0$$

~~$\int d\tau$~~

→ Dealing with $\frac{d}{d\tau}(\delta x^\mu)$:

$$\int d\tau g_{\mu\nu} \frac{dx^\nu}{d\tau} \frac{d}{d\tau}(\delta x^\mu) = - \int d\tau \frac{d}{d\tau} \left[g_{\mu\nu} \frac{dx^\nu}{d\tau} \right] \delta x^\mu$$

$$= - \int d\tau \left[\frac{\partial g_{\mu\nu}}{\partial x^\rho} \frac{dx^\rho}{d\tau} \frac{dx^\nu}{d\tau} + g_{\mu\nu} \frac{d^2 x^\nu}{d\tau^2} \right] \delta x^\mu$$

$$\Rightarrow \delta\tau = \frac{1}{2} \int d\tau \left[g_{\mu\nu, \rho} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} \delta x^\rho - \left(g_{\mu\nu, \rho} \frac{dx^\rho}{d\tau} \frac{dx^\nu}{d\tau} + g_{\mu\nu} \frac{d^2 x^\nu}{d\tau^2} \right) \delta x^\mu - \left(g_{\mu\nu, \rho} \frac{dx^\rho}{d\tau} \frac{dx^\mu}{d\tau} + g_{\mu\nu} \frac{d^2 x^\mu}{d\tau^2} \right) \delta x^\nu \right] = 0$$

$$\Rightarrow \frac{1}{2} \int d\tau \left[g_{\mu\rho} \frac{d^2 x^\mu}{d\tau^2} + (\partial_\mu g_{\nu\rho} + \partial_\nu g_{\rho\mu} - \partial_\rho g_{\mu\nu}) \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} \right] \delta x^\rho = 0$$

~~for~~ ⑧ Where did the boundary terms go?
 → "Cauchy boundary conditions".

From the least action principle:

$$\Rightarrow g_{\mu\nu} \frac{d^2 x^\mu}{d\tau^2} + \underbrace{\frac{1}{2} (\partial_\mu g_{\nu\rho} + \partial_\nu g_{\rho\mu} - \partial_\rho g_{\mu\nu})}_{\text{?}} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} = 0$$

$$\Rightarrow g^{\rho\sigma} g_{\mu\rho} \frac{d^2 x^\mu}{d\tau^2} + \frac{1}{2} g^{\rho\sigma} (\partial_\mu g_{\nu\rho} + \partial_\nu g_{\rho\mu} - \partial_\rho g_{\mu\nu}) \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} = 0$$

$$\Rightarrow \delta_\mu^\sigma \frac{d^2 x^\mu}{d\tau^2} + \underbrace{\frac{1}{2} g^{\rho\sigma} (g_{\nu\rho,\mu} + g_{\rho\mu,\nu} - g_{\mu\nu,\rho})}_{\text{?}} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} = 0$$

$$\Gamma_{\nu\mu}^\sigma = \Gamma_{\mu\nu}^\sigma$$

[Note: We have derived $\Gamma_{\mu\nu}^\sigma$ from first principles!!]

$$\Rightarrow \boxed{\frac{d^2 x^\sigma}{d\tau^2} + \Gamma_{\mu\nu}^\sigma \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} = 0}$$

→ This is why the action principle is so fundamental (and powerful!) — we derived an essential feature of curved spacetime geometry without knowing diff. geom. !!

ONE MORE THING!!

Q How does the geodesic equation evolve
change under the ~~of~~ linear transformation:

$$\tau \rightarrow \lambda = a\tau + b, \quad a, b \text{ constant?}$$

$$\frac{d^2x^\mu}{d\tau^2} = \frac{d\lambda}{d\tau} \left(\frac{d}{d\lambda} \left(\frac{d\lambda}{d\tau} \frac{dx^\mu}{d\lambda} \right) \right) = a^2 \frac{d^2x^\mu}{d\lambda^2}$$

$$\frac{dx^\mu}{d\tau} = \frac{d\lambda}{d\tau} \frac{dx^\mu}{d\lambda} = a \frac{dx^\mu}{d\lambda}$$

$$\Rightarrow a^2 \left[\frac{d^2x^\mu}{d\lambda^2} + \Gamma_{\nu\sigma}^\mu \frac{dx^\nu}{d\lambda} \frac{dx^\sigma}{d\lambda} \right] = 0 \quad \boxed{\text{Invariant!!}}$$

→ Such parameters λ s.t.

$\boxed{\lambda = a\tau + b}$ for which the
geodesic eq. is invariant is called
Affine parameter!!